VF20 QUICK START

1 Connect power supply, motor and peripherals (See pages 4 and 5)

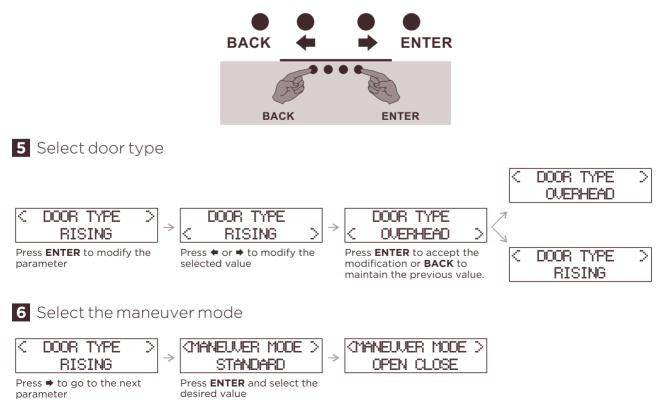


If the motor has a brake, follow the instructions on page 24.

2 Power the control panel, the screen will turn on

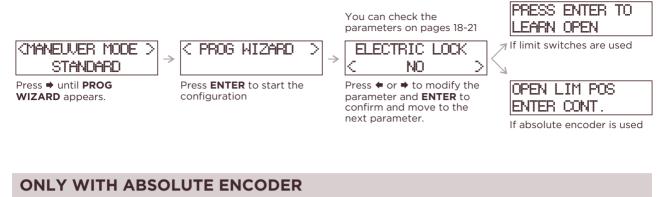


- 3 Test motor operation with ← (close) and → (open). Maneuver is in deadman mode and slow speed. If the direction of rotation is not correct, exchange the motor **U** and **V** wiring. Adjust the limit switches (if any). When finished, leave the door closed.
- 4 Enter the menu by pressing **BACK** and **ENTER** simultaneously



7 Perform the maneuver programming procedure. Make sure you have closed the door first.

Do not enter **OPTIONS** and **SETTINGS** menus, not necessary for programming

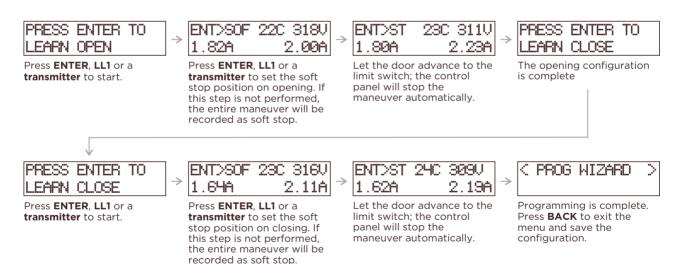


Move the door with \blacklozenge (close) and \blacklozenge (open) and bring it first to the opening limit, press **ENTER** and then to the closing limit and press **ENTER** again.

Advance in the same direction at least 50cm before setting a limit for proper encoder configuration.

The position of the encoder appears on the screen; it should increase when opening and decrease when closing.

| OPEN LIM POS → OPEN LIM POS → CLOSE LIM POS → CLOSE LIM POS 376 → 4294 → 4294 → 148 |
|---|
|---|



8 Test operation and tune **OPTIONS** and **SETTINGS**

Use **LL1**, **LL2** or a **transmitter** to test the operation of the maneuver. If necessary, modify the corresponding parameters in **OPTIONS** and **SETTINGS.**

